RELATIVISTIC POSITIONING SYSTEMS AND GRAVITATIONAL PERTURBATIONS

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ESA PECS project

- ESA PECS Relativistic Global Navigation System
- 2011-2014
- continuation of the ESA ACT Ariadna projects (A. Čadež, U. Kostić, P. Delva)

gravitational perturbations

- refine the description of the system
- same concept (ABC, recovery of constants of motion, refining the Hamiltonian)

Delva, Čadež, Kostić Inter-Satellite Emission Links (ISL) coordinates Clock Realization of correction the ABC and data reference frame reduction Hamiltonian: Schwarzschild Satellites constants metric of motion Emission all relevant coordinates gravitational perturbations Coordinate transformation to User the ABC reference frame

Project goals

- 1. add first order gravitational perturbations to the Schwarzschild metric
 - find perturbation coefficients describing all known gravitational perturbations: due to the Earth's multipoles, tides, rotation; gravity of the Moon, the Sun, and planets (Venus, Jupiter)
- 2. solve the perturbed geodesic equations
 - use Hamiltonian formalism \rightarrow perturbation theory \rightarrow obtain time evolution of 0th order constants of motion
 - (Ariadna study: analytic solutions of oth order)

3. find accurate constants of motion

- using inter-satellite distances measured over many periods
- stability and degeneracies
- (Ariadna study: done for Oth order)

4. refine values of gravitational perturbation coefficients

- use residual errors between orbit prediction and orbit determination through inter-satellite communication
- accuracy of position
- possible scientific applications

3.1 Introduction

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Perturbations

gravitational perturbations:

- Earth's multipoles
- the Moon
- the Sun
- Earth's tides
- planets (Venus, Jupiter)
- Earth's rotation

non-gravitational effects:

- Solar radiation pressure
- Earth's albedo



Fig. 3.1. Order of magnitude of various perturbations of a satellite orbit. See text for further explanations. Montenbruck & Gill, 2005

Perturbations in Schwarzschild background

- Schwarzschild background (spherically symmetric, time independent): $g_{\mu\nu}^{(0)}$
- linear perturbation theory
- perturbations: $h_{\mu\nu} \ll g^{(0)}_{\mu\nu}$ perturbed metric: $g_{\mu\nu} = g^{(0)}_{\mu\nu} + h_{\mu\nu}$
- Einstein's equation:

$$R_{\mu\nu} - \frac{1}{2} g_{\mu\nu} R = \frac{8\pi G}{c^4} \mathcal{T}_{\mu}$$

General equations:

$$R_{\mu\nu} - \frac{1}{2}g_{\mu\nu}R = -8\pi T_{\mu\nu}$$

$$T_{\mu\nu} = T_{\mu\nu}^{(0)} + \delta T_{\mu\nu} \qquad R_{\mu\nu}^{(0)} - \frac{1}{2}g_{\mu\nu}^{(0)}R^{(0)} = -8\pi T_{\mu\nu}^{(0)}$$
$$R_{\mu\nu} = R_{\mu\nu}^{(0)} + \delta R_{\mu\nu} \qquad R_{\mu\nu}^{(0)} - \frac{1}{2}g_{\mu\nu}^{(0)}R^{(0)} = 0 \implies R^{(0)} = 0 , \ R_{\mu\nu}^{(0)} = 0$$

$$\begin{split} h_{\alpha \ ;\mu\nu}^{\ \alpha} - h_{\mu \ ;\nu\alpha}^{\ \alpha} - h_{\nu \ ;\mu\alpha}^{\ \alpha} + h_{\mu\nu; \ \alpha}^{\ \alpha} + g_{\mu\nu}^{(0)} (h_{\alpha \ ; \ \lambda}^{\ \lambda \ \alpha} - h_{\lambda \ ;\alpha}^{\ \lambda \ \alpha}) + g_{\mu\nu}^{(0)} h_{\lambda\sigma} R^{(0)\lambda\sigma} - h_{\mu\nu} R^{(0)} = -16\pi \delta T_{\mu\nu} \\ \\ Equation A \end{split}$$

Regge & Wheeler (1957) approach

spherical harmonics expansion:

$$h_{\mu\nu} = \sum_{l=2}^{\infty} \sum_{m=-l}^{l} (h_{\mu\nu}^{lm})^{(o)} + (h_{\mu\nu}^{lm})^{(e)}$$

 $(h_{\mu\nu}^{lm})^{(o)}$... odd parity $(h_{\mu\nu}^{lm})^{(e)}$... even parity

- solution of Equation A:
- for odd: 3 functions of r
- for even: 7 functions of r

gauge transformations

Regge & Wheeler (RW)(1957) $x'^{\nu} = x^{\nu} + \xi^{\nu}$ $h'_{\mu\nu} = h_{\mu\nu} + \xi_{\mu;\nu} + \xi_{\nu;\mu}$ • odd: $\xi^0 = \xi^1 = 0$ $\xi^d = \Lambda(t, r) \epsilon^{cd} Y^{lm}{}_{.d}$ for d = 2, 3• even: $\xi^0 = M_0(t, r) Y^{lm}(\theta, \phi)$ $\xi^1 = M_1(t, r) Y^{lm}(\theta, \phi)$ $\xi^2 = M_2(t,r)\partial_{\theta}Y^{lm}(\theta,\phi)$ $\xi^3 = M_2(t,r) \csc^2 \theta \partial_{\phi} Y^{lm}(\theta,\phi)$

$$\begin{split} (h_{\mu\nu}^{lm})^{(o)} &= \begin{bmatrix} \begin{array}{c|c} 0 & 0 & -h_0^{lm} \csc \theta \partial_{\varphi} & h_0^{lm} \sin \theta \partial_{\theta} \\ \hline 0 & 0 & -h_1^{lm} \csc \theta \partial_{\varphi} & h_1^{lm} \sin \theta \partial_{\theta} \\ \hline \star & \star & 0 & 0 \\ \hline \star & \star & 0 & 0 \\ \end{array} \end{bmatrix} Y^{lm}(\theta,\varphi) \\ (h_{\mu\nu}^{lm})^{(e)} &= \begin{bmatrix} \begin{array}{c|c} H_0^{lm}(1 - \frac{r_s}{r}) & H_1^{lm} & 0 & 0 \\ \hline \star & H_2^{lm}(1 - \frac{r_s}{r})^{-1} & 0 & 0 \\ \hline 0 & 0 & r^2 K^{lm} \sin^2 \theta \\ \end{array} \end{bmatrix} Y^{lm}(\theta,\varphi) \end{split}$$

- odd f.: 2, even f.: 4
- vacuum, time independent: $H_0^{lm} = H_2^{lm} = H^{lm}$ (RW 1957, Zerilli 1970) $H_1^{lm} = 0$

 $h_{1}^{lm} = 0$

r_s.... Schwarzschild radius

even parity functions

we get solutions for $r > r_s$:

$$H^{lm}(r) = B_{lm} \frac{P_l(r_s/r)}{r^l(r-r_s)}$$

$$K^{lm}(r) = B_{lm} \frac{R_l(r_s/r)}{r^{l-1}(r-r_s)^2}$$

where:

$$P_l(y) = \sum_{i=0}^{\infty} p_i y^i = 1 + \frac{1}{2}(l-1)y + \frac{(l+2)l(l-1)}{4(2l+3)}y^2 + \frac{(l+3)(l+1)l(l-1)}{24(2l+3)}y^3 + O(y^4)$$

$$R_l(y) = \sum_{i=0}^{\infty} r_i y^i$$

odd parity functions

RW (1957), Zerilli (1970) • vacuum, time independent: $h_1^{lm} = 0$

$$h_0^{lm}(r) = A_{lm} r^{-l} S_l(r_s/r)$$
 where $S_l(y) = \sum_{i=0}^{\infty} s_i y^i$

• purely relativistic

Earth's multipoles - time independent

• Newtionian gravitational potential:

• perturbation:

$$\Phi_{N} = \sum_{lm} \frac{N_{lm}}{r^{l+1}} Y^{lm}$$
• perturbation:

$$g_{00} = c^{2} \left(1 - \frac{r_{s}}{r} \right) \left(1 + \frac{1}{c^{2}} \sum_{lm} H_{0}^{lm}(r) Y^{lm}(\theta, \phi) \right)$$
• lim $c \rightarrow \infty$:

• $\lim c \to \infty$

$$B_{lm} = 2N_{lm}$$

connection between Newtonian multipole momenta and expansion coefficients

Earth rotation

3 effects:

1. Kerr effect due to rotating monopole, to 1st order: Allison (1989)

$$h_{t\varphi}^{Kerr} = h_{\varphi t}^{Kerr} = -\frac{r_s}{r} a \sin^2 \theta \quad \text{where} \quad a = \frac{\Gamma}{M_{\oplus}c}$$

• or with RW, odd parity function l=1, m=0:

$$A_{10} = ar_s \sqrt{\frac{4\pi}{3}} \longrightarrow h_0^{10}(r) = \sqrt{\frac{4\pi}{3}} a \frac{r_s}{r} S_1(r_s/r)$$



2. Kerr effect due to rotating (higher) multipoles – negligible in 1st order (Hartle 1967)



Fig. 3.1. Order of magnitude of various perturbations of a satellite orbit. See text for further explanations. Montenbruck & Gill, 2005

3. time dependent multipoles

• perturbations vary with (small) ω :

$$\Phi_{\rm N} = \frac{GM_{\oplus}}{r} + \Delta\Phi_{\rm N} \qquad \Delta\Phi_{\rm N}(t, r, \theta, \varphi) = \sum_{lm} \frac{N_{lm}}{r^{l+1}} Y^{lm}(\theta, \varphi) e^{\pm im\omega t}$$

$$\begin{split} H^{lm}(T,r) &= e^{\mathrm{i}mkT}\tilde{H}^{lm}(r) , \qquad T = ct \\ K^{lm}(T,r) &= e^{\mathrm{i}mkT}\tilde{K}^{lm}(r) , \\ H_1^{lm}(T,r) &= e^{\mathrm{i}mkT}\tilde{H}_1^{lm}(r) , \end{split}$$

• RW (1957), Zerilli (1970): $H_1^{lm} \neq 0$

• series in frequency:

$$\tilde{H}^{lm} = \sum_{i=0}^{\infty} k^{2i} \tilde{H}^{lm(i)} , \quad \tilde{K}^{lm} = \sum_{i=0}^{\infty} k^{2i} \tilde{K}^{lm(i)} , \quad \tilde{H}_{1}^{lm} = \sum_{i=0}^{\infty} k^{2i+1} \tilde{H}_{1}^{lm(i)}$$

- to 1st order
- even:

$$\tilde{H}_{1}^{lm(0)} = -\frac{r^2}{l(l+1)} \left[\frac{6}{r} + \frac{1}{r_s} (l-1)(l+2)(H^{lm} + K^{lm}) - \frac{4}{r(1-r_s/r)} K^{lm} \right]$$

 $\tilde{H}^{lm} = \tilde{H}^{lm(0)} \qquad \tilde{K}^{lm} = \tilde{K}^{lm(0)}$

• odd: solutions not flat at $r \rightarrow \infty$

Earth tides

- solid and ocean tides
- time dependent Earth's gravitational potential
- similar to time dependent multipoles: different frequency and phase, amplitude
- literature with data on tides



Celestial bodies

Moon, Sun, planets

- post Newtonian description PPN: Einstein, Infeld, Hoffmann (1938), Brumberg (2007), Landau&Lifshitz (1980)
 OR
- expansion –
 similar as multipoles



• for each celestial body:

$$\begin{split} U &= \sum_{i} \frac{GM_{i}}{\|\mathbf{r}_{i} - \mathbf{r}\|} \qquad [h_{\mu\nu}] = \frac{2U}{c^{2}} \operatorname{diag}(-1, 1, 0, 0) \\ U &= \sum_{l=0}^{\infty} \sum_{m=-l}^{l} r^{l} M_{lm}^{\operatorname{cel}} Y^{lm}(\theta, \varphi) \\ M_{lm}^{\operatorname{cel}} &= \sum_{i} \frac{4\pi GM_{i}}{(2l+1)r_{i}^{l+1}} Y^{lm*}(\theta_{i}, \varphi_{i}) \end{split}$$

Hamiltonian formalism

$$h_{\mu\nu} = h_{\mu\nu}^{\text{multipoles}} + h_{\mu\nu}^{\text{tides}} + h_{\mu\nu}^{\text{cel}} + h_{\mu\nu}^{\text{Kerr}}$$

$$\mathcal{H} = \underbrace{\frac{1}{2} g^{\mu\nu(0)} p_{\mu} p_{\nu}}_{\mathcal{H}^{(0)}} - \underbrace{\frac{1}{2} h^{\mu\nu} p_{\mu\nu}}_{\Delta \mathcal{H}}$$

• 1st order correction to constants of motion

$$\dot{f} = \frac{\mathrm{d}f}{\mathrm{d}\lambda} = \frac{\partial f}{\partial\lambda} + \{f, \mathcal{H}\}$$



- for Kerr effect: Alisson (1989) equations for f
- for others: in Mathematica

Software/Hardware

• Time-consuming minimization procedures

- Ariadna study: 1 10 minutes for 0^{th} order
- add perturbations → even more timeconsuming
- Parallelization
 - mostly independent pairs of satellites → ideal for parallelization
 - GPUs may run few 10 100 times faster than a single CPU



CPU Multiple Cores

GPU Hundreds of Cores

Next steps

simulate satellite orbits in Schwarzschild background with 'gravitationally perturbed' time dependent 'constants of motion'



communicate – refine their constants of motions use residual satellites and errors to refine the Hamiltonian, i.e. obtain improved parameters of perturbations

- Model the Galileo GNSS directly in general relativity including gravitational perturbations
- To what level can this new approach improve the accuracy and stability of the Galileo GNSS reference frame
- Scientific utilization of the GNSS, e.g. relativistic gravimetry, geology...

comments and suggestions?

Thank you!